Fabrication of a new class of porous media models for visualization studies of multiphase flow processes

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The conventional wet-chemistry techniques used for the fabrication of porous media models exhibit some shortcomings with regard to the control of the structural parameters of pores etched either on glass or on plastic plates. A new method of fabrication of pore network micro-models, using an excimer laser LIGA technique, is presented. First, the microstructure is etched on a thin PMMA layer by using as input data the pore depth distribution (10–25 μ m) and the pore width-to-depth aspect ratio distribution (~1–4). Then, the void space is filled with a layer of nickel (total thickness~300 μ m) which, in turn, is covered by a thick layer of copper (~1700 μ m) by using micro-electroforming. Finally, and after a series of mechanical treatments, a metal insert, which is a negative replica of the target microstructure, is produced and used for the printing of a large number of identical structures on PMMA plates with hot embossing. Each plastic model is glued with a thin PMMA cover foil by using a spin coating technique. In this manner, pore network models of well-controlled pore dimensions are produced. It is found that the depth of pores is well-controlled, whereas the depth of each intersection region (node) is almost equal to the sum of the depths of the two intersected capillaries (bonds). The aforementioned features in combination with the broad pore depth and width range (10–100 μ m) make the new micro-models representative of real porous media such as natural formations (e.g. sedimentary rocks, soils). Preliminary experiments of two-phase immiscible displacement performed on the new models confirm their applicability to visualization studies of multiphase transport processes in porous media. © 2002 Kluwer Academic Publishers

1. Introduction

Multi-fluid transport processes in porous media are encountered in a wide variety of practical applications either of industrial interest, such as the oil and gas recovery from underground rock reservoirs [1-5], or of environmental significance, such as the risk assessment & in situ remediation of soils and aquifers contaminated by agricultural chemicals, landfill leachates, industrial wastes, etc [6, 7]. Porous media models, that is pore networks etched in glass or plastic have been used in numerous visualization studies of multiphase transport processes (e.g. two- and three-phase immiscible displacement) in order to clarify the pore-scale mechanisms [8–17], identify the mesoscopic patterns of fluid distribution [17, 18-22], and determine the dependence of mesoscopic transport coefficients (e.g. residual saturation of fluids at the end points, two-phase relative permeabilities, drainage/imbibition capillary pressure curves, etc) on microstructural parameters of pores, fluid properties and process dynamics [8, 15, 18, 21, 23, 24]. Furthermore, such experimental studies became the basis for the development and evaluation of pore network simulators for multiphase transport processes [19–21, 25, 26].

In general, pore networks constructed with wetchemistry techniques are unable to retain certain structural properties of real porous media [11, 16, 20]. Specifically, (a) the pore depth is not a well-controlled parameter and is usually adjusted by changing the duration of glass etching and sintering, (b) the variability of the pore depth (which is the smallest dimension) is very low and (c) the pore dimensions are relatively high (>50 μ m). These built-in characteristics of pore network models result in relatively low values of capillary pressure, high mean value (~100 μ m) and small variation of the equivalent capillary diameter distribution, as

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well as in small ($\sim 1-1.2$) chamber-to-throat equivalent capillary diameter aspect ratio [8, 11, 16]. In addition, the precise reproduction of a structure in many copies is difficult to be attained with chemical or photo etching techniques, and models constructed from the same pattern (mask) always exhibit certain differences caused by small variations in exposure times [8, 11, 16]. The pore structure of natural porous formations (e.g. sedimentary rocks such as sandstones and carbonates, soils, etc) is characterized by wide pore size distributions, medium and large values of chamber to throat diameter aspect ratio ($\sim 2-10$) and mean pore sizes ranging from 100 μ m to lower than 0.1 μ m [27].

The objective of the present work is the construction of pore network models by using an excimer laser ablation technique, in order to avoid all above-mentioned shortcomings of the conventional models. In this manner, multiple identical micro-models, which are representative of real porous media (e.g. natural formations), are expected to be constructed. Such models will enable us to perform visualization multiphase transport experiments under realistic conditions.

2. Fabrication of micro-models

Pore network models can be constructed either by etching directly the final micro-structure on a plate with an excimer laser ablation technique or by using a series of moulding/replication processes (laser-LIGA technique) [28]. In the first case, the direct production of a large number of identical micromodels requires the iterative operation of the excimer laser for a long period under unaltered conditions. Such a procedure is economically inefficient and exceptionally time-consuming. In the second case, the excimer laser ablation technique is used just once for the etching of the structure on a thin plastic layer and then micro-electroforming produces a metal insert, which is a metallic negative replica of the microstructure (laser-LIGA technique). This metal insert can be used for the fabrication of an enormous multitude of identical microstructures on plastic plates with high precision, by using either hot embossing or injection moulding techniques. Obviously, the excimer laser-LIGA process [28] is much cheaper than a direct method and allows the production of a great number

of identical microstructures. This is particularly important for the case of pore network models intended to be used iteratively in multiphase flow experiments. The basic steps of the excimer laser LIGA process, that was used for the fabrication of pore network micromodels are described in the following.

1. Initially, the dimensions of the pores are selected and the laser is programmed for the construction of the microstructure (Fig. 1). The characteristics of the target structure are fed as input data to the laser computer. The



Figure 1 Structural characteristics of pore network micromodels.

Depth (μm) Frequency Aspect ratio Frequency Input pore-depth and pore width-to-depth aspect ratio distributions 10 0.2 1.0 0.15 15 0.3 2.0 0.35 20 0.3 3.0 0.35 25 0.2 4.0 0.15 Mean depth = 17.7 μ m Mean aspect ratio = 2.5St. Dev of asp.ratio = 0.92 St. Dev. of depth = $10.5 \ \mu m$ Selected pore-depth and pore width-to-depth aspect ratio distributions 10 0.203 1.0 0.174 15 0.260 2.0 0.304 20 0.348 3.0 0.348 25 0.189 4.00.174 Mean depth = 17.6 μ m Mean aspect ratio = 2.52St. Dev. of depth = 9.14 μ m St. Dev of asp.ratio = 0.945

TABLE I Pore-depth and pore width-to-depth aspect ratio distributions

pattern of the microstructure is a square network that consists of 39 columns \times 30 rows of straight pores of constant length (500 μ m), variable depth (10–25 μ m) and variable width to depth aspect ratio (1–4). The dimensions of the network are 20 mm \times 15 mm, whereas each column (x-axis) and each row (y-axis) is characterized by constant pore depth and width which are

selected randomly from pre-specified discrete size distributions (Table I). Given that the total number of columns and rows is quite small (=69) the statistical distributions of the selected pore dimensions (Table I) are expected to differ slightly from the input ones. Two troughs of dimensions $15 \text{ mm} \times 2 \text{ mm}$ and depth $50 \mu \text{m}$ are placed as inlet and outlet ports to ensure uniform



Figure 2 Measurement of the pore depth of micromodels with the aid of the program WYKO from pictures of UV-Interferometry. The depth is almost uniform (\sim 23 μ m) along the pore cross-section (*x*-axis profile) and exhibits very low variation (<1 μ m) along the pore length (*y*-axis profile).



Figure 3 Detail of the intersection region between one column and one row of the pore network.

and homogeneous fluid distribution outside the network (Fig. 1). The communication of the microstructure with external fluid sinks is ensured through two large holes placed close to the troughs (Fig. 1).

2. A titanium wafer of diameter 10 cm is covered with liquid PMMA monomer that is thermally polymerized. Afterwards, the surface is mechanically polished with a thickness tolerance better than 10 μ m. The thickness of the formed polymer layer is about 300 μ m. The pore network model is etched on the surface of the polymer layer by excimer laser ablation [28]. The rate of material removal depends on the type of material, the pulse energy and the number of pulses (wavelength = 193 nm). Since the process is controlled by a computer, the operational parameters of the excimer laser are properly adjusted to be consistent with the pore depths and widths.

3. Microelectroforming is used to produce a micromould insert [28]. First, the surface of PMMA is sputter coated with a thin film of titanium (~50 nm) and silver (~150 nm) to become electrically conductive. Then, a layer of pure nickel is deposited on the etched structure using as an electrolyte, a solution of nickel sulphamate, boric acid and special additives at 50°C and pH ~4.2. The nickel growths with a rate of 12 μ m/hr until forming a layer of 300 μ m. To reinforce the metal insert, a copper layer is deposited on the nickel layer by using as electrolyte, a copper sulphate solution at pH ~0–1. The copper growths with a rate of 40 μ m/hr, until forming a layer of 1700 μ m.

4. The metal matrix is cut from the Ti wafer by wire cutting. After cutting, a thin Ti film remains on the electroformed PMMA/Ni/Cu system that can be removed either wet chemically at this stage, or

TABLE II Comparison between theoretically selected and actually measured pore dimensions on a fabricated PMMA micro-model

Column	Depth (μ m)		Width (μ m)			Depth (μ m)		Width (μ m)	
	Select.	Meas.	Select.	Meas.	Row	Select.	Meas.	Select.	Meas.
1	20	24.1	80	86.0	1	15	16.4	30	39.9
2	5	10.3	15	20.8	3	10	11.3	30	36.7
3	10	11.7	40	47.2	4	15	10.3	15	21.7
4	20	20.0	20	33.5	5	20	19.4	20	31.2
5	15	16.7	30	41.3	6	20	23.8	80	83.8
6	10	11.4	30	39.0	7	20	23.5	60	66.7
8	20	23.5	60	66.7	10	25	28.3	50	52.7
10	15	17.6	45	54.3	11	20	23.7	40	52.7
11	10	9.9	20	24.3	14	15	17.3	60	60.1
12	20	23.5	40	52.3	16	10	9.7	20	24.3
13	20	20.0	20	28.4	17	25	24.8	25	39.9
15	10	10.6	10	14.1	19	10	11.7	40	47.2
17	20	25.2	40	41.3	23	25	26.6	75	79.9
38	25	28.4	50	50.0					



Figure 4 Overview of the entire surface of a pore network micro-model.



Figure 5 (a) Microscopic detail of an intersection region (node) by focusing on the bottom of the perpendicular adjacent pores. (b) Microscopic detail of the intersection region by focusing on the bottom of the horizontal adjacent pores.

thermo-mechanically during hot embossing. The polymer layer of PMMA is dissolved and the rough surface of the metal matrix is polished mechanically with conventional polishing whereas the insert is cut in its final dimensions with wire cutting.

5. The metal matrix is used as a mould insert and identical PMMA models are constructed from it with hot embossing. Some traces of the titanium remaining on the surface of matrix are removed during this stage. Care is taken to properly adjust the temperature and force in the hot embossing chamber in order to achieve the optimal quality. It was found that a temperature close to 160° C and a force close to 1000 N/m^2 gave the optimal results. The pore depth and width of micromodels are expected to differ slightly from the corresponding input values of the pattern because of imperfections developed during electroforming and bending stresses developed during hot embossing. The pore widths and depths were measured on the final micromodels by using UV-interferometry with the aid of the program WYKO (Fig. 2). The measurements confirmed that there is a small deviation with regard to



Figure 6 (a) Detail of the connection of the pore network with the trough in a corner region. (b) Detail of the connection of the etched pore network with the trough in the middle region.

pore widths, whereas pore depths remain almost unaltered (Table II). In addition, measurements of the depth of adjacent pores and their intersection region (crosslinkages of a row with a column, Fig. 3) indicated that the depth of each intersection (node) was almost equal to the sum of the depths of the two adjoining pores (bonds) (Table III).

6. Inlet and outlet holes are drilled in the middle of the troughs of each PPMA micromodel. Then a thin PMMA foil (thickness $\sim 125 \ \mu m$) is glued on the plate of each micromodel by using a spin coating technique.

A very thin layer of a glue is spread on the surface of the foil and the etched plastic plate is placed on it. The entire system is centrifuged at a specified revolution rate for a finite time span until a uniform thin layer is formed, and then is left in a UV-oven for several minutes until the glue hardens.

A metal insert and seventeen pore network models (Fig. 4) were constructed by using the excimer laser LIGA process. The quality of the structural characteristics of micromodels was checked before their gluing



Figure 7 Overview of the fabricated pore network.

with cover foil plates by using optical microscopy and UV-interferometry and was found satisfactory (Figs 5–7). Specifically, any intersection region was always deeper than its adjacent pores (Fig. 5), whereas no discontinuities were formed in the junctions of the pore network with the troughs (Fig. 6a and b).

3. Two-phase flow experiments

Some preliminary two-phase immiscible displacement experiments were performed on the new PMMA pore network models (Fig. 4). Simple imbibition experiments, where the air (non-wetting fluid) occupying the pore space is displaced by n-decane (wetting fluid), were performed (Fig. 8) at two constant inflow rates (250 m1/hr, 500 m1/hr) by using a Harvard Syringe pump (Type: 55-2219). Successive shortcuts of the displacement process were taken by a Camera (Sony) and were directly recorded on a hard disk by using a fully automated real-time digitizer (DPS) that is capable of capturing pictures with a velocity of 25 frames/sec. Time-dependent representative successive short-cuts of a displacement experiment are shown in Fig. 9. After the breakthrough of the invading phase (Fig. 9, shortcut 17) the system tends very fast to steady state (Fig. 9, shortcuts 18–20). In multiphase processes through porous media, the ratio of viscous to capillary forces is expressed by the capillary number Ca [8, 18, 23] which is given by

$$Ca = \mu u / \sigma \tag{1}$$

TABLE III Sample measurements of the depth of pores and their junctions (nodes) in two different regions of an unglued and a glued micromodel

Pore element		Regi (ung Mea	ion A lued model) n depth (μm)	Region B (glued model) Mean depth (μ m)
Row 1		11.3		15.7
Row 2		15.5		21.1
Column 3		12.6		24.8
Column 4		28.9		11.9
Node a		22.4		39.7
Node b		40.0		26.9
Node c		27.5		45.8
Node d	44.9			31.9
		3	4	
	1	a	b	
-	2	c	d	

where μ is the viscosity of the invading phase, u is the injection velocity and σ is the interfacial tension of the two fluids.

The depth of each intersection region (node) of pores (bonds) is equal to the sum of the depths of the adjacent intersected pores. Hence, during the displacement of air



Figure 8 Microscopic detail of a region of the micromodel that is occupied by n-decane (dark continuous phase) and air (light isolated blobs).



Figure 9 Successive shortcuts of the immiscible displacement of air by *n*-decane at capillary number $Ca = 10^{-6}$. (Continued.)



Figure 9 (Continued.)



Figure 9 (Continued.)

from n-decane, the capillary pressure exerted on interfaces encountered in pores (bonds) is always greater than that exerted on interfaces created in intersection regions (nodes). So, the filling of the pores (bonds) with the wetting fluid is favored against the filling of the intersection regions (nodes). For this reason, most ganglia of the non-wetting fluid are trapped in intersection regions (Fig. 9) rather than in pore clusters, as it usually occurs during displacement experiments in conventional glass-etched models [8, 11, 18, 20, 21, 23].

4. Conclusions

Pore network micro-models were fabricated on transparent plastic PMMA plates by using a new method based on the excimer laser LIGA technique. A metal moulding insert was first fabricated through excimer laser ablation and electroforming, then a large number of identical plastic etched micro-models was replicated by using a hot embossing technique, and finally each model was glued with a cover thin foil with spin coating. The pore network models are intended to be used in visualization experimental studies of multiphase flow through porous media. Measurements of the structural characteristics of the micromodels confirmed their improved features against the older ones produced by using wet chemistry techniques. Specifically, the new models exhibit well-controlled pore depth and width distributions, a broad pore depth range which is by one order of magnitude ($\sim 20 \ \mu m$) lower than that of the conventional glass models ($\sim 100 \ \mu m$), and pore intersection regions (nodes) deeper than their adjacent pores (bonds). In this manner, the capillary properties of the new models are expected to be close to those of prototype porous media such as natural formations (e.g. sedimentary rocks, soils, etc). The applicability of the new models to multiphase transport studies was confirmed by performing certain preliminary air/n-decane immiscible displacement experiments on them.

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